VECTORS IN TWO DIMENSIONS

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Unit Outcomes:

Unit

After completing this unit, you should be able to;

- *know basic concepts and specific facts about vectors.*
- perform operations on vectors.

Main Contents

- 7.1 Introduction to vectors and scalars
- 7.2 Representation of a vector
- 7.3 Addition and subtraction of vectors and multiplication of a vector by a scalar

7.4 Position vector of a point

Key Terms Summary Review Exercises

INTRODUCTION

FROM PREVIOUS GRADES, YOU KNOW ABOUT MEASUREMENTS OF DIFFERENT KINDS SU-WEIGHT, TEMPERATURE, DISTANCE, ANGLE MEASURE, AREA, ETC. SUCH QUANTITIES NUMBERS AS THEIR MEASURE (WITH SOME UNIT OF MEASUREMENT). FOR EXAMPLE, TI A ROOM IS 3 M, THE WEIGHT OF A QUINTAL IS 100 KG, THE DISTANCE BETWEEN TWO CLASSROOM IS 8 M, THE TEMPERATURE OF A NORMALTIPHERSORNASOFCA TRIANGLE ABC IS 6 CM, ETC. NOT ALL QUANTITIES, HOWEVER, ASSUME ONLY A SINGLE REAL N THEIR MEASURE. THERE ARE SOME QUANTITIES THAT ASSUME MEASURES INVOLVING I

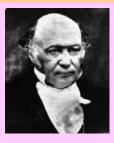
EXAMPLE SUPPOSE WE ARE IN SCHOOL A, AND SOMEONE HAS TOLD US THAT HE STUINERBY SCHOOL B THAT ASWAY. DO WE HAVE ENOUGH INFORMATION TO FIND B? OF COURSE NOT, BECAUSE B COULD BE AT ANY POINT ON A CIR RADIUSM CENTRED AT A. IN ADDITION TO THE DISTANCE, WE NEED TO KNODIRECTION IN ORDER TO FIND B.

THERE ARE MANY PHYSICAL QUANTITIES WHOSE MEASUREMENTS INVOLVE BOTH MADIRECTION. THESE INCLUDE VELOCITY, FORCE, ACCELERATION, ELECTRIC OR MAGNISUCH QUANTITIES ARE CHARLETODAY VECTORS HAVE MANY APPLICATIONS. ALL BRANCOF CASSICAL AND MODERN PHYSICS ARE REPRESENTED BY USING THE LANGUAGE VECTORS ARE ALSO USED WITH INCREASING FREQUENCY IN THE SOCIAL AND BIOLOGIC THIS UNIT, YOU WILL DEAL WITH VECTORS, IN PARTICULAR VECTORS IN TWO DIMENSIC

HISTORICAL NOTE:

Sir William Rowan Hamilton (1805-1865)

The study of vectors started with Hamilton's invention of quaternions. Quaternions were developed as mathematical tools for the exploration of physical space. As quaternions contained both scalar and vector parts, difficulties arose when these two parts were treated simultaneously.



Scientists soon learned that many problems could be dealt with by considering vector parts separately, and the study of vector analysis began.

7.1 INTRODUCTION TO VECTORS AND SCALARS

Group Work 7.1

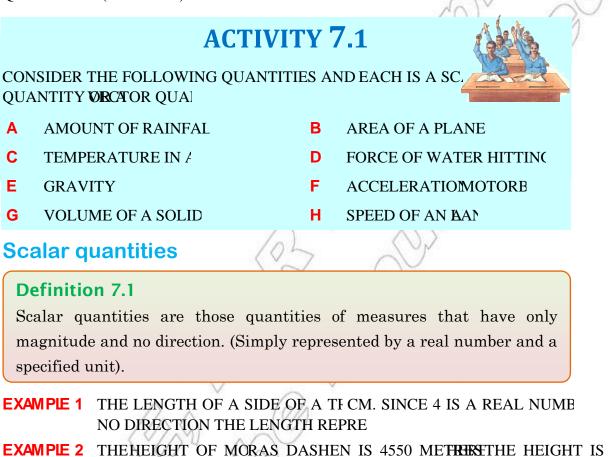
292

1 DISCUSS SOME QUANTITIES THAT CAN BE EXPRESS USIN& SINGLE MEASUREMENT (WITH UNITS).



2 DISCUSS SOME QUANTITIES THAT REQUIRE BOTH SIZE AND ENCOUNTION.

IN GENERAL, THERETWO TYPES OF PHYSICAL ME: THOSENVOLVING ONLY MAGNITUDE AND NO D, CALLEDDATS AND OTHERSOLVING MTUDE AND A DEFINITE DIRECTION, CADISED MANY APPLICATIONS OF MATHEMATICS ⁷ AND BIOLOGICAL SCIENCES AND ENGINEERING, SCIENTISTSQUANTITIES THAT HAVE BOTH MAGNITUDECTION. AS MENTIONED ABOVE, EXAMPLES INCLU FORCE, VELOCITY, ACCELERATION, ANIT IS USEFUIBEOABLE EXPRESS THESE QUANTITIES (VECTORS) BOTH GEOMETRICALLY



- REHESENTED BY A SINGLE REA. HENCE IT REPRESENTS
- **EXAMPLE 3** THEDAYTIME TEMPEROF MERCURY RISES **COSLN**CE 30 IS A REAL NUMBER, TTEMPERATURE REPRESENTS A SCALAR.

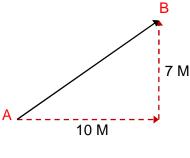
Vector quantities

Definition 7.2

Vector quantities are those quantities of measure that have both magnitude (length) and direction.

EXAMPLE 4 THE VELOCITY OF A C KM/H IN THE DIRECTION CONTRACTOR.

EXAMPLE 5 SUPPOSE HELEN M, FROM A, 1M TO THE EAST [E] AND M TO THE NORTH [N] TO REACISHOW, AS A VECTOR; SHEDENL DISPLAC.





SOLUTION: TAKEN TOGETHER, THE DISTANCE AND DIRECTION OF THE CALLED **THE** accement FROM A TO B, AND IS REPRESENTED BY FIGURE 7.1

THE ARRONAD TELLS US THAT WE , ABOUT THE DISPLACEMENT OF HELE B. THIS IS AN EXAMPLE OF A

7.2 REPRESENTATION OF A VECTOR

ACTIVITY 7.2



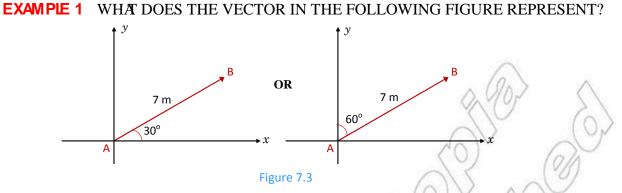
- 1 DISCUS&LGEBRAIC AND GEOMETRIC RES OF VECTORS.
- **2** REPRESENT THE ' \overrightarrow{OP} GEOMETRICALLY, WHERE O IS AND P = (2, 3) IN THy-COORDINATE SYSTEM.
- 3 DISCUSS TMEGNITUDE AND DIRECTION (
- 4 FIND THE MAGNITUDE AND THE DIRECTIO \overrightarrow{OP} .
- 5 WHEN ARE TWO VECTOF

294

A VECTOR CAN BE REPRESENTED EITHEF OR GEOMETRICOHIEN, THOST CONVENIENT WAY OF REPRESENTING VECTORS IS GEOMETR VECTOR IS REPRESENTED BY AN ARROW (SEGMENT.

Figure 7.2

WHEN A VECTOR IS REPRESENTED B(see \overrightarrow{OP} ABOVET, HE POINT O IS CALL initial point AND P IS CALLEI terminal point. SOMETIMES, VECTORS ARE RE USING LETTERS OR A LETTER WITH A B $\ell \vec{u}$, \vec{v} , ETC.



SOLUTION: THE VECTOR HAS A LENGTH OF 7 M AND DIRECTION NORMEMIST 30 [E30°N] (OR A DIRECTION OF NORMALITY ON ONE). ITS INITIAL POINT IS A AND ITS TERMINAL POINT IS B.

WHAT DO YOU THINK IS THE MAGNITUDE (LENGTH) OF A VECTOR AND THE DIRECTION (

EXAMPLE 2 THE FOLLOWING ARE EXAMPLES OF VECTOR REPRESENTATION. CAN YOU I THEIR LENGTHS AND DIRECTIONS?

Hint: USE RULERAND PROTRACTOR

Magnitude (length) of vectors

THE MAGNITUDE (LENGTH) OF THE VERCESTORPLAY IS THE LENGTH OF THE LINE SEGMENT FROM THE INITIAL POINT O TO THE TERMINAL POINT P, (THE LENGTH OF THE DIRECTED L

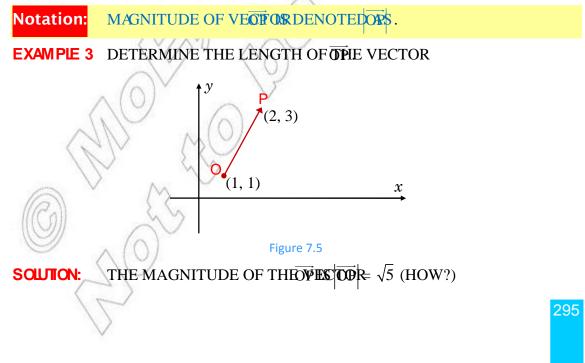


Figure 7.4



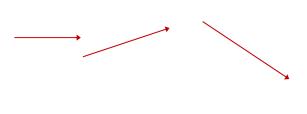


Figure 7.6

EXAMPLE 5 A FORCE OF 10 POUNDS IS EXERTED VERTICALLY DOWN TO THE SURFACE OF EARTH AND A FORCE OF 20 POUNDS IS EXERTED PARALLEL TO THE SURFACE OF EARTH FROM LEFT TO RIGHT. THE GEOMETRIC REPRESENTATION IS

Figure 7.7

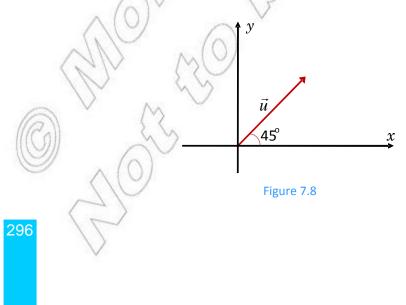
HER, NOTICE THAT THE ARROWS (DIRECTED LINE SEGMENTS) ARE DRAWN WITH LENGT TO THE MAGNITUDES. THE ARROW REPRESENTING 10 POUNDS IS HALF THE LENGTH REPRESENTING 20 POUNDS.

FROM THIS, WE REALIZE THAT THE MAGNITUDE OF A VECTOR IS REPRESENTED BY THE I ARROW THAT REPRESENTS THE VECTOR.

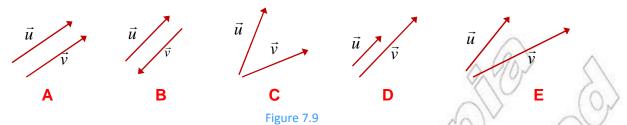
Direction of vectors

THE DIRECTION OF A VECTOR IS THE ANGLE THATAINS ROOM NITHEABY REPRESENTS THE VECTOR) WITH THE HORIZONTAL LINE AT ITS INITIAL POINT (OR WITH THE VERTICAL LINE AT ITS DIRECTIONS).

EXAMPLE 6 THE DIRECTION OF THE AVEROMARTHE HORIZONTAL LINE AT ITS INITIAL POIN AS REPRESENTED BELOW, OR 454 (E)



CONSIDER THE FOLLOWING PAIRIOF PAIRIOF



WHADO YOU OBSERVE? DO THEY HAVE THE SAME LENGTH? DO THEY HAVE THE SAME I

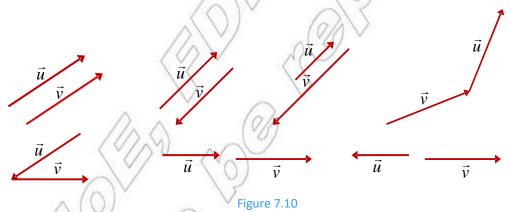
THE TWO VECTORSIANCE THE SAME LENGTH AND THEY HAVE THE SAME DEVORECTION. VECTORS INAVE THE SAME LENGTH BUT THEY HAVE OPPOSETEWORVECTIORS. IN HAVE THE SAME LENGTH AND DIFFERENT DIRECTIONS. ON VEVDINE REARS IN MICH, BUTHEY HAVE SAME DIRECTION. AND THE TWO FFERTORS IN LENGTH AND DIRECTION.

Note: 1 IFTWO VECTORS HAVE OPPOSITE DIRECTIONS, THEY ARE CALLED OPPOSITE

2 VECTORS THAT HAVE EITHER THE SAME OR OPPOSITE DIRECTIONS AR PARALLEL VECTORS.

EXAMPLE 7 FROM THE VECTORS GIVEN IN ABOVE, B AND ARE PARALLEL VECTORS.

WHENWE REPRESENT VECTORS BY USING DIRECTED ARROWS AS GIVEN ABOVE, WE C SIMILARITIES OR DIFFERENCES IN LENGTH OR DIRECTION. WHAT DO YOU OBSERV FOLLOWING VECTORS?

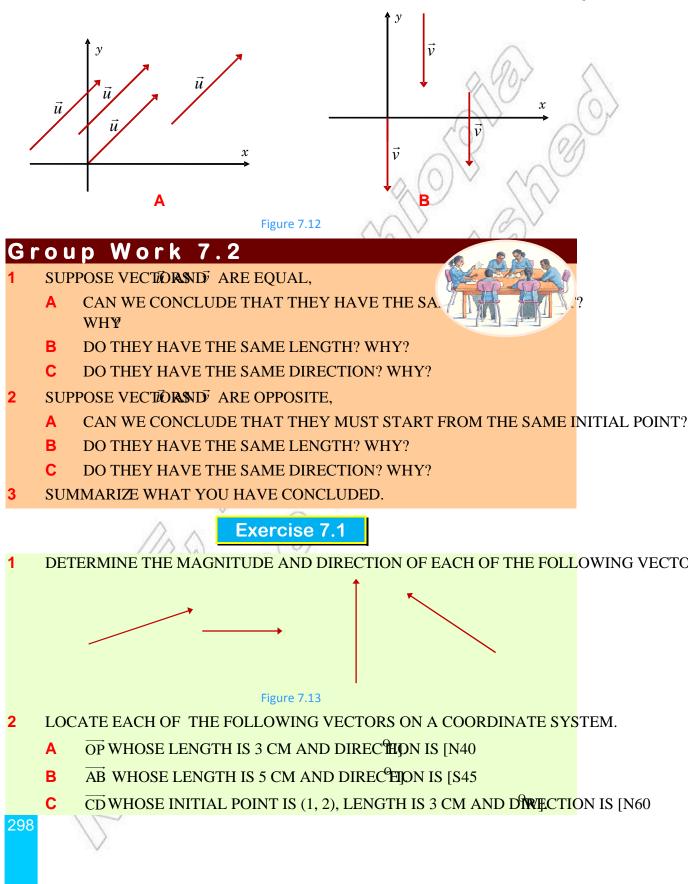


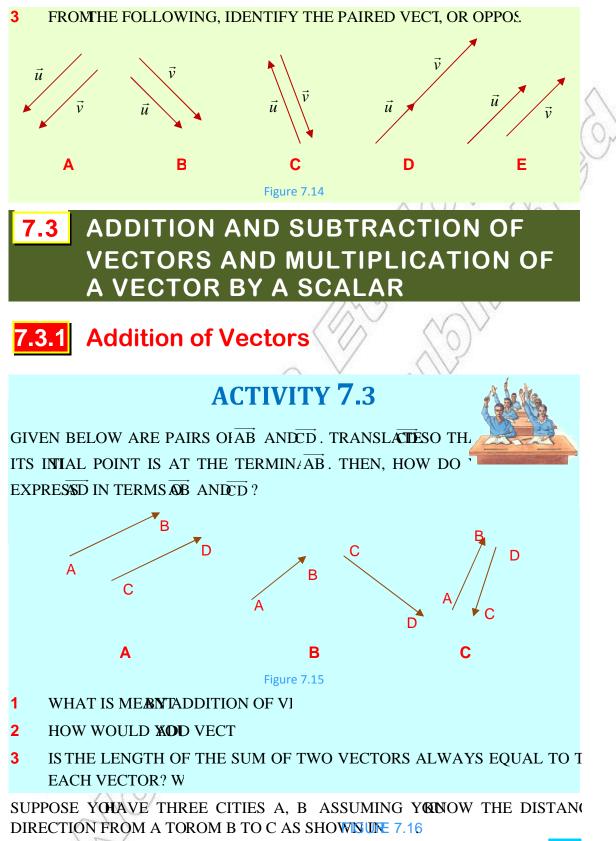
Equality of vectors

TWO VECTORS ARE SAID TO BE EQUAL, IF THEY HAVE THE SAME LENGTH AND THE SAM

EXAMPLE 8 THE FOLLOWING TWO VECANDERS, ARE \vec{u} EQUIA SINCE THEY HAVE THE SAME LENGTH AND THE SAME DIRECTION. THE ACTUAL LOCATION OF THESE VECTORS IS NOT SPECIFIED. WE CALL SUCH VECTORS free vectors

EXAMPLE 9 INEACH OF THE DIAGRAMS BELOW, ALL THE VECTORS ARE EQUAL.



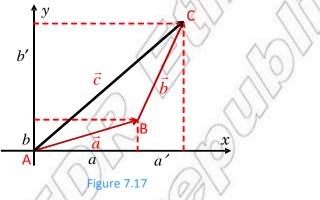


IF YOU WANT TO GO DIRECTLY FROM A TO C, WHAT WOULD BE THE C DETANCE AND DIRECTION?

THE FIRST THING TO NOTICE IS THAT IF THE THREE CITIES DO NOT LIE IN A STRAIGHT LINE, THEN THE DISTANCE FROM A TO C WILL NOT BE EQUAL TO THE SUM OF THE DISTANCES FROM A TO B AND FROM B TO C.

ALSO, THE DIRECTION MAY NOT BE RELATED IN A SIMPLE OR OBVIOUS WAY TO THE TWO SEPARATE DIRECTIONS. Figure 7.16

YOU WILL SEE, HOWEVER, THAT THE SOLUTION IS EASY IF WE WORK WITH THE COMPO DISPLACEMENT VECTORS. LET THE COMPONENTS OF THE VECTOR FROM A TO B IN T NORTH DIRECTIONS **BE ANNOR**OM B TO C IN THE EAST AND NORTH **DIRECTIONS** BE a'RESPECTIVELY. THEN WE CAN SEE THAT THE COMPONENT OF THE DISPLACEMENT VEC C IN THE EAST DIRECTION **ISNOHIN** THE NORTH DIRECTION IS b + b'



FROM THIS, WE CAN CONCLAIDED THATC $OR\vec{a} + \vec{b} = \vec{c}$.

WE SHALL DISCUSS ADDITION OF VECTORS USING TWO AND THE parallelogram law OF ADDITION OF VECTORS.

Group Work 7.3

- **1** DISCUSS THE TRIANGLE LAW OF VECTOR ADDITION
- 2 DISCUSS THE PARALLELOGRAM LAW OF VECTOR A.
- 3 WHAT RELATION AND DIFFERENCE DO BOTH LAWS HAV

Triangle law of addition of vectors

CONSIDER THE FOLLOWING(1).

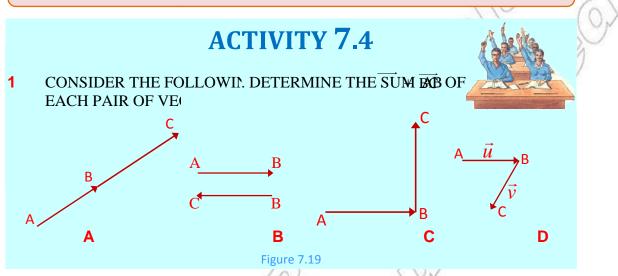
OBSRVE THAT $\overrightarrow{BC} = \overrightarrow{AC}$.



B Figure 7.18

Definition 7.3 Triangle law of vector addition

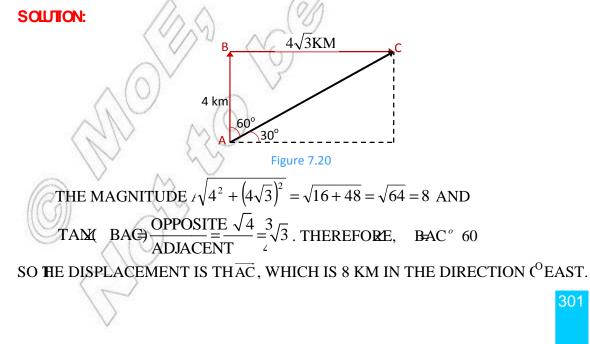
Let \vec{a} AND \vec{b} be two vectors in a coordinate system. If $\vec{a} = \overrightarrow{AB}$ AND $\vec{b} = \overrightarrow{BC}$ then their sum, $\vec{a} + \vec{b} = \overrightarrow{AB} + \overrightarrow{BC}$ is the vector represented by the directed line segment \overrightarrow{AC} . That is $\vec{a} + \vec{b} = \overrightarrow{AB} + \overrightarrow{BC} = \overrightarrow{AC}$.



BY WRITING **WHE**TOR ADI $\overrightarrow{AB} + \overrightarrow{BC}$, WE ARE LOOKING FOR THAT VECTOR POINT IS A AND WHOSE TERMINAL POINT IS C. \overrightarrow{AC} IS SOMETIMES CATHE resultant displacement.

VECTOR ADDITION CAN BE DONE EITHER GRAPHICALLY OR BY SEPA COMPONENTS. WE SHEATULTHADDITION OF VECTOR COMPONENT.UNIT.

EXAMPLE 1 A CARRAVE4 KM TO THE NORTH AND THE DISPLACEMENT OF THE CAR FFINAROSITION



EXAMPLE 2 A PERSON MOVED 10 M TO THE EAST FROM A TO B AND THEN 10 M TO THE V FROM TO A. FIND THE RESULTANT DISPLACEMENT.

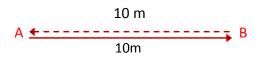
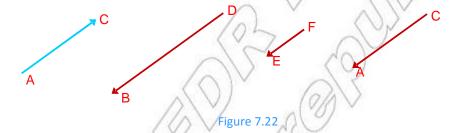


Figure 7.21

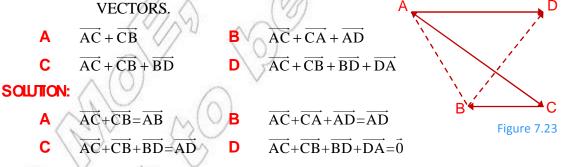
SOLUTION: HERE WE SEE THAT THE PERSON ENDS UP AT A, HENCE HZERODSPLACEMENT FROM THIS WE SEE THAT IF WE HANDEA, THEN THE SUM OF THESE VECTORS $\overrightarrow{B} + \overrightarrow{BA}$ VANISHES IN THE SENSE THAT THE INITIAL POINT AND TERMINAL POINT COINCIDE. SUCH A VECTOR IS VERALLADIA IS DENOIDED YO OR SIMPLY 0. IARE, $\overrightarrow{BA} = 0$.

GIVENAC, IF \vec{u} IS A VECTOR PARALCEBUTION OPPOSITE DIRECTION STRAID TO BEANopposite vector TOAC. –AC REPRESENTS THE VECTOR EQUAL IN MAGNITUDE B OPPOSTE IN DIRECTION TOHAT IS, AC = CA. NOTICE THAT F AC = AC – AC = 0

EXAMPLE 3 THE FOLLOWING ARE ALL OPPOSITE. TO VECTOR

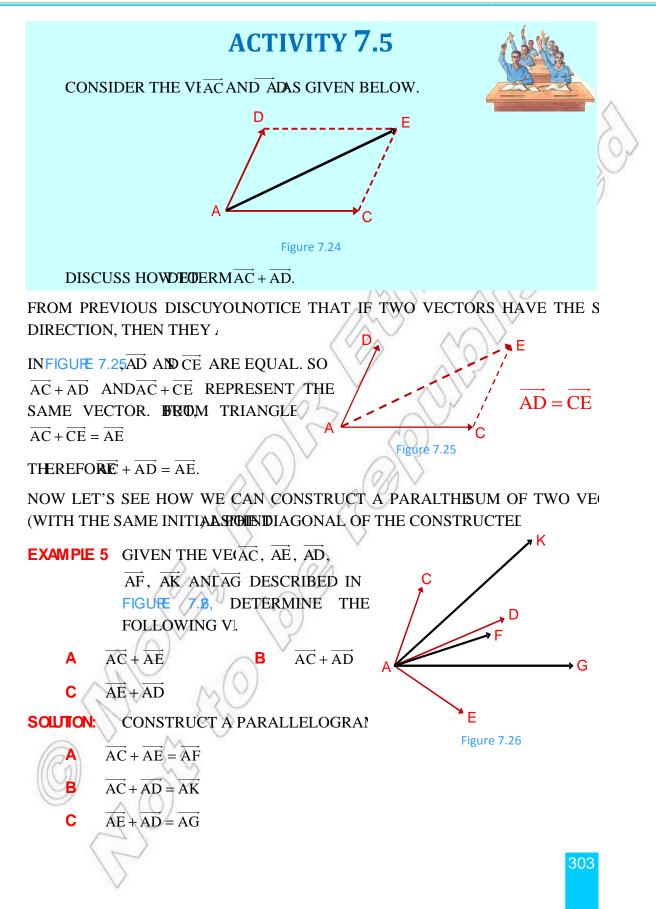


THAT IS, VECTOR, SDB AND FE ARE ALL OPPOSITING UT NOT EQUAL IN MAGNITUDE) EXAMPLE 4 CONSIDER THE VERTORSA, CB AND AD DETERMINE THE FOLLOWING



Parallelogram law of addition of vectors

IN THE ABOVE, WE SAW HOW THE TRIANGLE LAW OF AD**PPLICX BLEWETERRSTISEA** INITIAL POINT OF ONE VECTOR IS THE TERMINAL POINT OF THE OTHER. WE MAY SOM VECTORS WHOSE INITIAL POINT IS THE SAME, YET WE NEED TO FIND THEIR SUM.



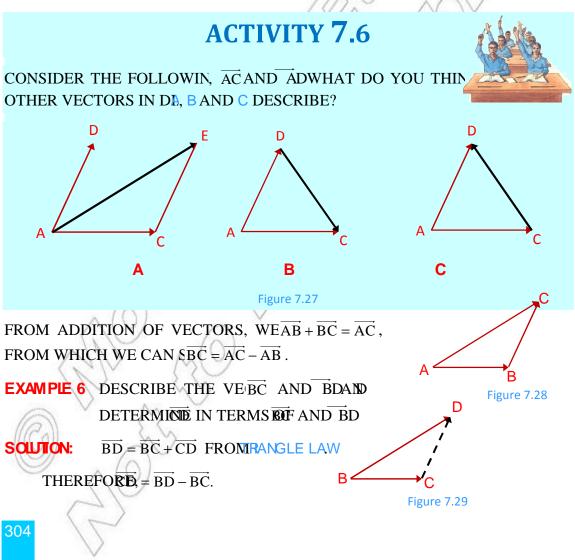
Subtraction of vectors

Group Work 7.4

IF YOU HAVE VECTEORIC AND ACSUCH THAT = $\overrightarrow{AB} + \overrightarrow{BC}$

- **A** HOW WOULD YOU RE $-\overrightarrow{AB}$ GEOMETRICALLY?
- **B** CAN YOU SHOW GEOMETRIC $\overrightarrow{AC} \overrightarrow{AB} = \overrightarrow{BC}$?
- **C** DISCUSS VECTOR SUB, AND MULTIPLICATION OF A VECTOR
- D HOW DO YOU REPRESENT VECTOR SUBTRACTION AND SCALATOR GEOMETRICALLY

YOU HAVE DISCUSSED TION OF VECTORS THAT ARE GEOMETRICALLY DESINITIAL PODETIONE VECTOR THE TERMINAL OPOTNE OTHER WITHOUT CH. MAGNITUDE AND DIREOW YOU SHALL CONSIDER THESGEORIACTRIC ECTORS.



Multiplication of vectors by scalars

ACTIVITY 7.7

CONSIDER A VERTORND DETERM

A $\overrightarrow{AC} + \overrightarrow{AC}$ **B** $\overrightarrow{AC} + \overrightarrow{AC} + \overrightarrow{AC}$ **C** $-\overrightarrow{AC} - \overrightarrow{AC} - \overrightarrow{AC}$

WHAT DO YOU OBSERVE? IT SEEMS VERY $\overrightarrow{AC} + \overrightarrow{AC} = 2\overrightarrow{AC}$. GEOMETRICALL MEANS WE ARE DOUBLING THE MAGNITUDE (LENG \overrightarrow{AC} WITHOUT CHANGI DIRECTION.

IN THE SAME WAY **GAWEAVBAC**, $\frac{1}{2}\overrightarrow{AC}$, $-\overrightarrow{AC}$ AND- $2\overrightarrow{AC}$, THEIN $3\overrightarrow{AC}$ WE ARE

TRIPLING THE MAGNITIC DENDEWE ARE TAKING HALF OF THE IAC IN $\frac{1}{2}$ AC.

WHAT DO YOU THANKANE-2AC MEAN?

IF WE HAVE AC WHERE ANY REAL NUMBER, THEN DEPENDING C EITHER WE ARE ENLARGING THE \overline{MC} CONTROL ARE SHORTENING THE WE HAVE ARE SHORTENING THE DIRECTION AC ARE THE SAME, k < 0, THEN THE VECTORS AC ARE IN OPPOSITE DIRECTIONS.

Scalar multiplication of a vector

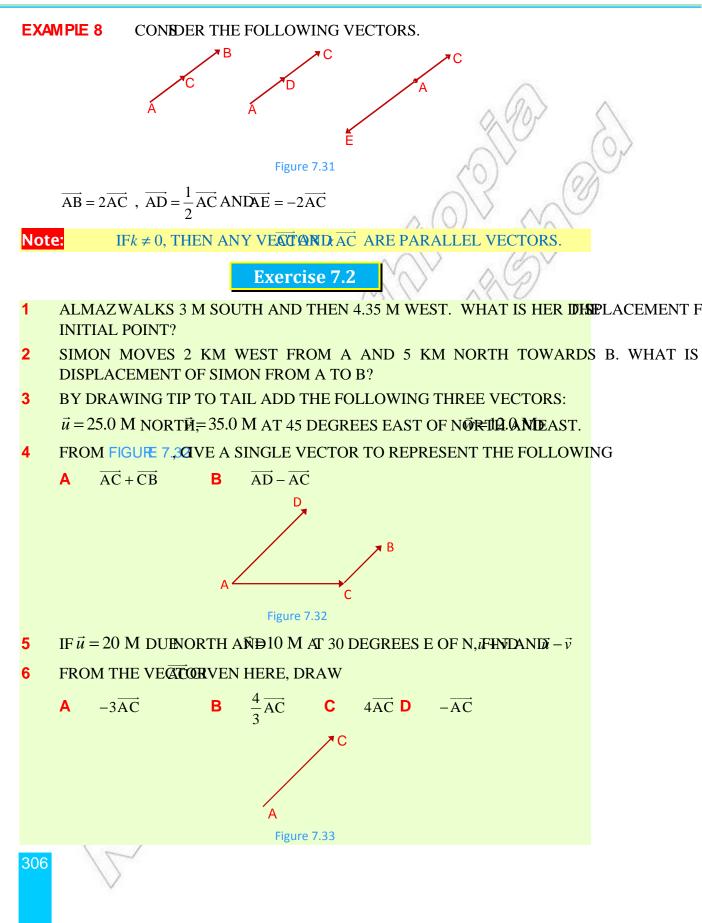
Definition 7.4

Let \overrightarrow{AC} be any given vector and *k* be any real number. The vector $k\overrightarrow{AC}$ is the vector whose magnitude is *k* times the magnitude of \overrightarrow{AC} and,

- **A** the direction of $k\overrightarrow{AC}$ is the same as the direction of \overrightarrow{AC} if k > 0
- **B** the direction of $k \overrightarrow{AC}$ is opposite to that of \overrightarrow{AC} if k < 0.

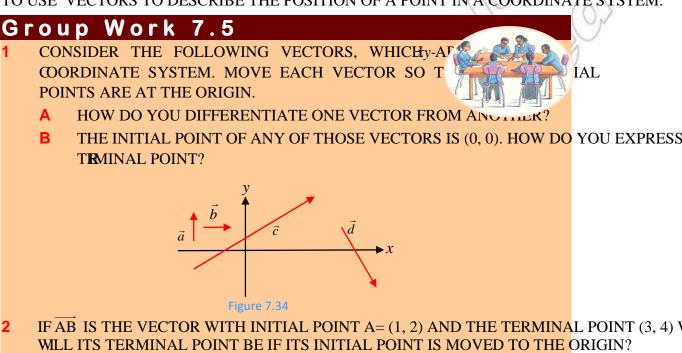
EXAMPLE 7 FIGURE 7.3(SHOWS VECAB AND THE RESULT OF MULTIPLYING I' RESULT OF MULTIPLY-1.

2AB Figure 7.30



7.4 POSITION VECTOR OF A POINT

UP UNTIL NOW, YOU HAVE USED THE GEOMETRIC REPRESENTATION OF VECTORS. NE DECUSS COMPONENTS OF VECTORS, AND VECTOR OPERATIONS THAT INCLUDE IN MAGNITUDE AND DIRECTION BY THE USE OF COMPONENTS OF A VECTOR. YOU WILL AN TO USE VECTORS TO DESCRIBE THE POSITION OF A POINT IN A COORDINATE SYSTEM.



3 IF $\vec{v} = \begin{pmatrix} 2 \\ 5 \end{pmatrix}$ REPRESENTS A VECTOR WITH INITIAL POINT AT THE ORIGIN, THEN HOW D

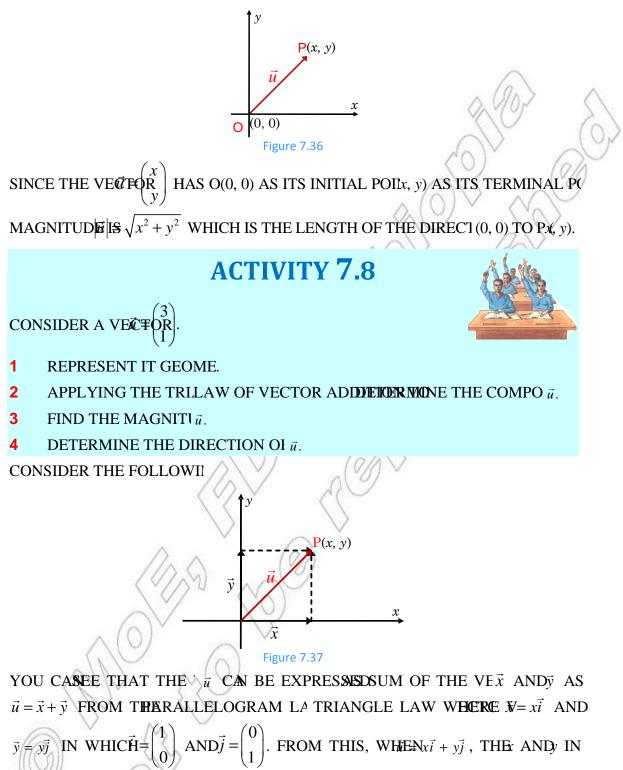
EXPRESSIN TERMS OF THE COORDINATES (2, 0) AND (0, 5)?

FROM PREVIOUS DISCUSSIONS, NOTICE THAT THE VECTORS REPRESENTED INTE 7.35THAT HAVE DIFFERENT INITIAL POINT&RE EQUAL. OF THESE VECTORS, THE ONE WHOSE INITIAL POINT IS THE ORIGIN IS GRADDED THE form OF THE PRESENTATION OF THE VECTOR (OR SIMPLY, THE x position vector).

ANAYTICALLY, WE USUALLY EXPRESS VECTORS IN COMPONENT FORM. WE DO THIS BY THE VECTOR WITH THE ORIGIN AS ITS INITIAL POINT AND WRITE THE COORDINATES POINT AS A "COLUMN VECTOR". FOR EXAMPLE, IN TWO-DOMENSIONS, OHS

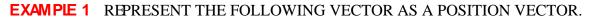
(0, 0) AND P IS THE POINTTHEN $= \begin{pmatrix} x \\ y \end{pmatrix}$.

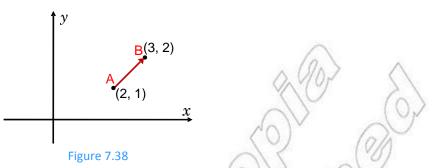
Note: SUCH COLUMN VECTORS ARE WRITTEN VERTICALLY, TO DOSTRDINATSESTHEM FROM ITS GEOMETRIC REPRESENTATION IS AS GIVEN BELOW.



 $\vec{u} = x\vec{i} + y\vec{j}$ ARE CAL**deED**ponents OF \vec{u} .

THESE COMPONENTS ARE USEFUL IN DETERMINING THE DIF





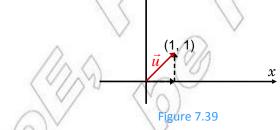
TO **E**PRESENT A POSITION V**AB**T**WE SIE**ED TO CONSTRUCT A VECTOR WHICH HAS THE SA IENGTH AND SAME DIRECTION AS **THE TVECTOR** WE NEED TO CONSTRUCT A VECTOR WHOS ORIGIN**O**S(0, 0) AND WHOSE TERMIN**(AL-IS**₁, $y_2 - y_1$) WHER**E** x_1, y_1) IS THE INITIAL **AND** y_2) IS THE TERMINAL POINT OF THE GIVEN VECTOR.

HENCE THE POSITION VECTOR OF ABLE INHERITOROVE IS

$$\vec{u} = \begin{pmatrix} 1 \\ 1 \end{pmatrix} OR_{\vec{u}} = \vec{i} + \vec{j} \text{ WHER} \vec{E} = \begin{pmatrix} 1 \\ 0 \end{pmatrix} AND\vec{j} = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

FROM THIS, WE CAN DETERMINE THE MAGNITUDE AND THE DIRECTION OF THE VECTOR.

EXAMPLE 2 FOR THE VECTOR GIVEN BY ITS GEOMETRIC REPRESENTATION IS GIVEN BHOW. FIND THE MAGNITUDE AND DIRECTION OF THE VECTOR.



- SOLUTION: FROM THIS GEOMETRIC REPRESENTATION AND FROM THE **ER**IGONOMETRIC THAT YOU DISCUSSED IN CHAPTER FIVE, WE CAN DETERMINE THE DIRECT VECTOR.
 - $TAN = \frac{OPPOSITE}{ADJACENT} TAN = = \frac{1}{1}$ THE ACUTE ANGLE WHOSE TANGENT VALUE IS 1 IS 45

HENCE, THE DIRECTION OF THE \emptyset . ECTOR IS 45

THE MAGNITUDE OF THE VECTOR AD $\Theta(1-0)^2 = \sqrt{2}$

EXAMPLE 3 FIND THE POSITION VECTOR OF THE FOLLOWING VECTORS WHOSE INI TEMINAL POINTS ARE AS GIVEN BELOW.

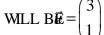
- A INITIAL POINT (1, 2) AND TERMINAL POINT (2, 5)
- B INITIAL POHNT3) ANDERMINAL POINT (1, 4)

SOLUTION:

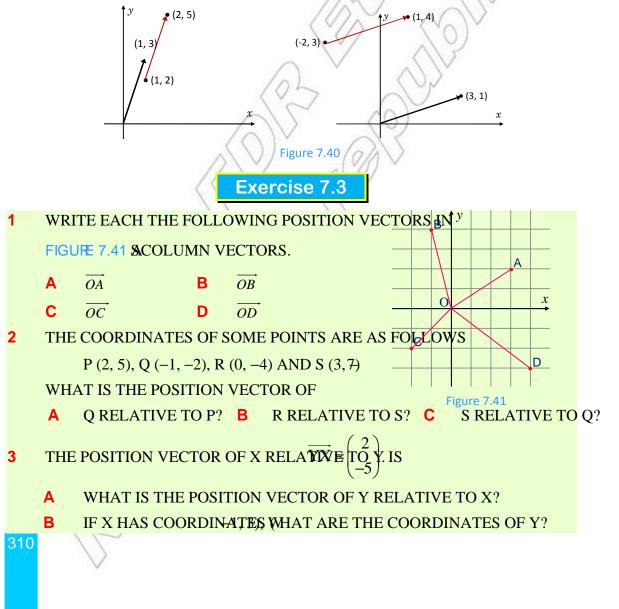
A THE POSITION VECTOR THE VECTOR WHOSE INITIAL POINT IS (1, 2) AND TERMIN PONTIS (2, 5) IS (24, 5-2) = (1, 3).

THAT IS, $= \vec{i} + 3\vec{j}$ WHICH WILL BE REPRESENTED AS

B THE POSITION VECTOR WHOSE INITIAL, BOAND IS (TERMINAL POINT IS (1, 40-13)(4-3) = (3, 1). THAT $15, = 3\vec{i} + \vec{j}$ WHICH



THEGEOMETRIC REPRESENTATION OF THESE VECTORS IS GIVEN BELOW.



- **C** IF M IS THE MIDPOINTY WHAT $\overrightarrow{\text{IS}}$ XM
- **D** WHAT IS THE POSITION $V \overrightarrow{OM}$?
- 4 REPRESENTE VECTORS, WHOSI(I) AND TERMINAL POIMRE GIVEN BE GEOMETRICALLY ON A CSYSTEM.
 - **A** I(1, 4) AND T(3, 2 **B** I(-2, 2) AND T(1, 4)
- 5 DETERMINE THE POSITION VECTOR OF EACH OF THQUESTION ABOVE.
- 6 DETERMINE THE MAGNITUDE AND THE DIRECTION OF EACH OF QUESTION ABOVE.

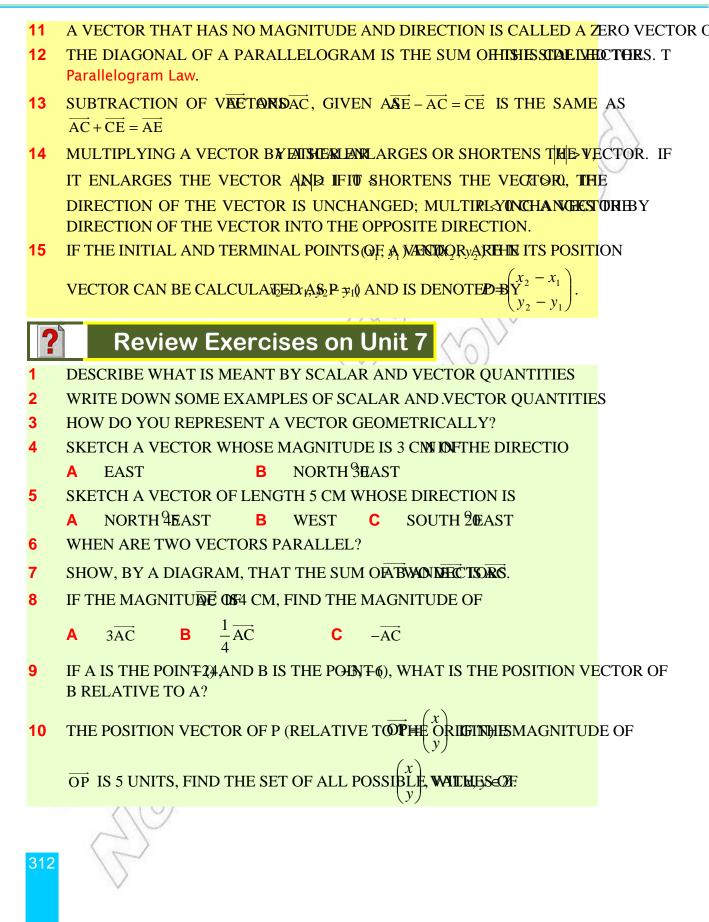
Key Terms

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addition of vectors	position vector
direction of a vector	scalar quantities
equality of vectors	subtraction of vectors
magnitude(length of) a vector	triangle law of vector addition
parallelogram law of vector addition	vector quantities

Summary

- 1 A scalar IS A MEASURE THAT INVOLVES ONI AND NO DIRECTIOE A VECTOR INVOLVES BOTH MAGNITUDE
- 2 A vector IS DENOTED A DIRECTED ARR**OENCISH** IS CALLED THE MAGE DIRECTION IT POINTS ITHE DIRECTION OF THE VECTOR
- **3** VECTORS INCLUDE VELOCITY, FORCE, ACCELERATION, ELE, ETC.
- **4** A VECOR IS REPRESENTED BY \overrightarrow{AOP}); THE POINT O IS CALLED THE IN AND P IS CALLED THE TERMINAL POINT. SOMETIMES, VECTORS ARI LETTERS OR A LETTER WITH A BAR \vec{u} , \vec{v} , ETC.
- 5 THE MAGNITUDE VELOCITY IS THE SPEED; THE MAGNITUDE OF A DISTANCE. THUS, SPEED AND DISTANCE ARE S
- 6 A MAGNITUDE IS ALWAYS A POSITI
- 7 VECTORS CAN BE DESCRIBED GEOMETRICALLY: GEOMETRICALLY DIRECTED ARROVGEBRAICALL'COLUMN VECTOR.
- 8 TWO VECTORS ARE SAlequal IF THEY HAVE THE SAME MAGNITUDE 4 DIRECTION.
- 9 IF TWO VECTORS HAVE SAME OR OPPOSITE DIRECTparallel.
- **10** FOR ANY TWO VEAB AND \overrightarrow{BC} , $\overrightarrow{AB} + \overrightarrow{BC} = \overrightarrow{AC}$ (THE TRIANGLY)



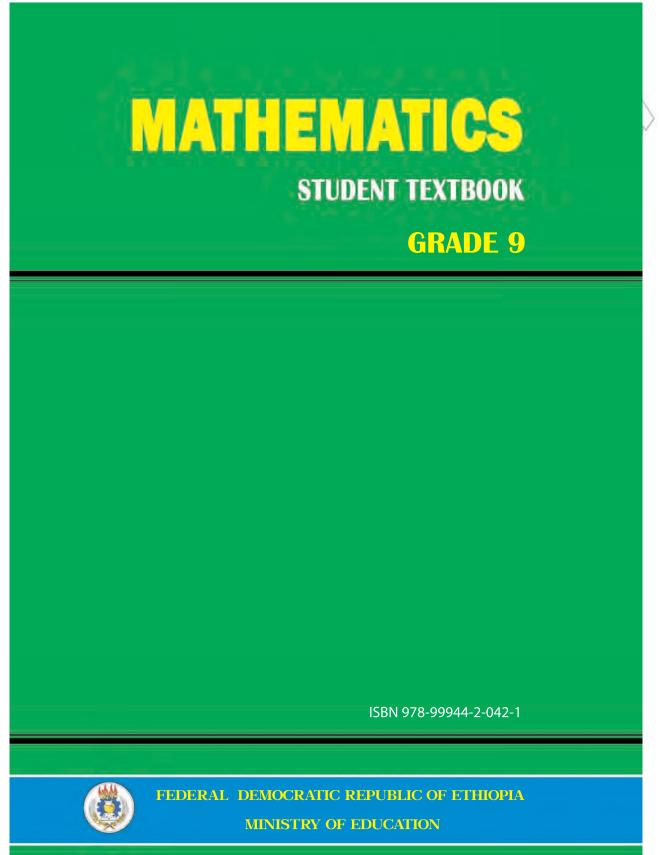
	sin	COS	tan	cot	sec	CSC	
0°	0.0000	1.0000	0.0000		1.000		90°
1°	0.0000	0.9998	0.0000	 57.29	1.000	 57.30	89°
2°	0.0349	0.9994	0.0349	28.64	1.000	28.65	88°
2 3°	0.0523	0.9986	0.0524	19.08	1.001	19.11	87°
4°	0.0698	0.9976	0.0699	14.30	1.002	14.34	86°
- 5°	0.0872	0.9962	0.0875	11.43	1.004	11.47	85°
6°	0.1045	0.9945	0.1051	9.514	1.006	9.567	84°
7°	0.1219	0.9925	0.1228	8.144	1.008	8.206	83°
8°	0.1392	0.9903	0.1405	7.115	1.010	7.185	82°
9°	0.1564	0.9877	0.1584	6.314	1.012	6.392	81°
10°	0.1736	0.9848	0.1763	5.671	1.015	5.759	80°
11°	0.1908	0.9816	0.1944	5.145	1.019	5.241	79°
12°	0.2079	0.9781	0.2126	4.705	1.022	4.810	78°
13°	0.2250	0.9744	0.2309	4.331	1.022	4.445	77°
13 14°	0.2419	0.9703	0.2493	4.011	1.020	4.134	76°
14 15°	0.2588	0.9659	0.2455	3.732	1.031	3.864	75°
16°	0.2756	0.9613	0.2867	3.487	1.040	3.628	74°
10 17°	0.2924	0.9563	0.3057	3.271	1.046	3.420	74 73°
18°	0.3090	0.9511	0.3249	3.078	1.040	3.236	73°
10°	0.3256	0.9455	0.3443	2.904	1.058	3.072	71°
20°	0.3420	0.9397	0.3640	2.747	1.064	2.924	70°
21°	0.3584	0.9336	0.3839	2.605	1.071	2.790	69°
22°	0.3746	0.9272	0.4040	2.475	1.079	2.669	68°
23°	0.3907	0.9205	0.4245	2.356	1.086	2.559	67°
24°	0.4067	0.9135	0.4452	2.246	1.095	2.459	66°
25°	0.4226	0.9063	0.4663	2.145	1.103	2.366	65°
26°	0.4384	0.8988	0.4877	2.050	1.113	2.281	64°
27°	0.4540	0.8910	0.5095	1.963	1.122	2.203	63°
28°	0.4695	0.8829	0.5317	1.881	1.133	2.130	62°
29°	0.4848	0.8746	0.5543	1.804	1.143	2.063	61°
30°	0.5000	0.8660	0.5774	1.732	1.155	2.000	60°
31°	0.5150	0.8572	0.6009	1.664	1.167	1.942	59°
32°	0.5299	0.8480	0.6249	1.600	1.179	1.887	58°
33°	0.5446	0.8387	0.6494	1.540	1.192	1.836	57°
34°	0.5592	0.8290	0.6745	1.483	1.206	1.788	56°
35°	0.5736	0.8192	0.7002	1.428	1.221	1.743	55°
36°	0.5878	0.8090	0.7265	1.376	1.236	1.701	54°
37°	0.6018	0.7986	0.7536	1.327	1.252	1.662	53°
38°	0.6157	0.7880	0.7813	1.280	1.269	1.624	52°
39°	0.6293	0.7771	0.8098	1.235	1.287	1.589	51°
40°	0.6428	0.7660	0.8391	1.192	1.305	1.556	50°
41°	0.6561	0.7547	0.8693	1.150	1.325	1.524	49°
42°	0.6691	0.7431	0.9004	1.111	1.346	1.494	48°
43°	0.6820	0.7314	0.9325	1.072	1.367	1.466	47°
45						1.440	
43 44°	0.6947	0.7193	0.9667	1.036	1.390	1.440	46°
	0.6947 0.7071	0.7193 0.7071	1.0000	1.036	1.390 1.414	1.440	46° 45°

Table of Trigonometric Functions



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Price ETB 47.10